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- (54) **ROTOR BLADE WITH OPTIMIZED TWIST DISTRIBUTION**
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- (51) **Int. Cl.**⁷ **B64C 27/467**; B64C 27/28
- (52) **U.S. Cl.** **244/7 R**; 244/17.11; 244/39; 416/223 R
- (58) **Field of Search** 244/7 A, 17.11, 244/17.23, 17.25, 39, 7 R; 416/55, 223 R

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(57) **ABSTRACT**

A rotor blade has a local geometric twist angle $\theta=f(r/R)$, with R being the blade span and r being the distance along the blade span from the axis of rotation. The blade has an inner region between an $(r/R)_{inner}=0.20\pm 0.04$ and a transition point at $(r/R)_{trans}=0.75\pm 0.04$, wherein θ_{inner} at $(r/R)_{inner}$ has a positive value and is greater than or equal to θ_{trans} at $(r/R)_{trans}$. A blade tip region includes a first portion between $(r/R)_{trans}$ and $(r/R)_{min}>(r/R)_{trans}$, wherein θ continuously decreases from θ_{trans} to θ_{min} at $(r/R)_{min}$, and $\Delta\theta_{tip1}=|\theta_{min}-\theta_{trans}|>3^\circ$, and a second portion between $(r/R)_{min}$ and the blade tip, wherein θ continuously increases from θ_{min} to θ_{tip} at the tip, and $\Delta\theta_{tip2}=|\theta_{tip}-\theta_{min}|$ is at least about 3° and no greater than about 20° . This geometry pushes the vortex trailed by the blade tip away from the blade and thus increases blade performance. In a preferred tiltrotor blade embodiment, $\Delta\theta_{inner}=|\theta_{inner}-\theta_{trans}|=32.5^\circ\pm 7.5^\circ$, θ continuously decreases from $(r/R)_{inner}$ to $(r/R)_{trans}$, $(r/R)_{min}=0.91\pm 0.04$, $\Delta\theta_{tip1}=7.5^\circ\pm 2.5^\circ$, and $\Delta\theta_{tip2}=10^\circ\pm 6^\circ$. In a preferred helicopter blade embodiment, $\Delta\theta_{inner}=|\theta_{inner}-\theta_{trans}|=20^\circ\pm 5^\circ$, θ continuously decreases from $(r/R)_{inner}$ to $(r/R)_{trans}$, $(r/R)_{min}=0.94\pm 0.04$, $\Delta\theta_{tip1}=5^\circ\pm 2^\circ$, and $\Delta\theta_{tip2}$ is from about 3° to about 10° . Another embodiment of the invention uses adjustable flaps to control $\theta=f(r/R)$ in an inboard region of a helicopter blade to optimize performance in hover and forward flight regimes.

19 Claims, 15 Drawing Sheets

